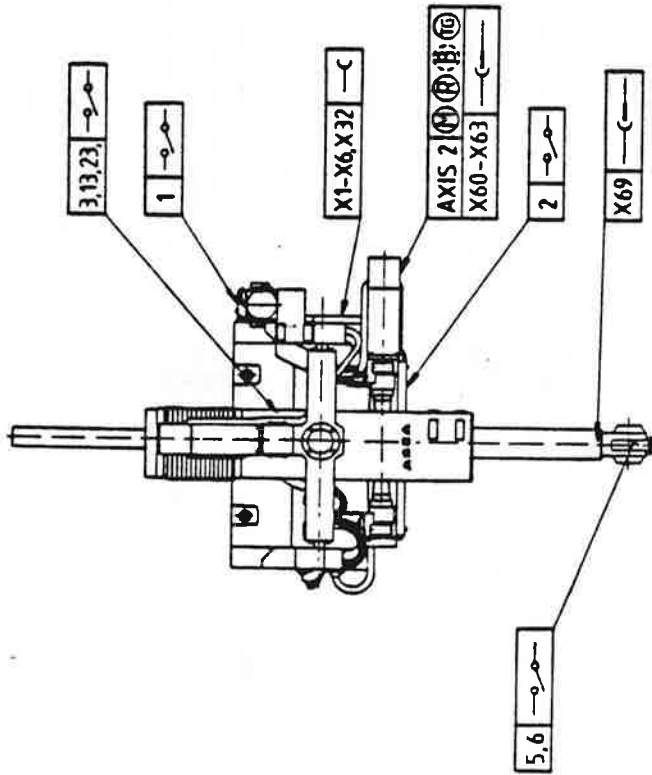
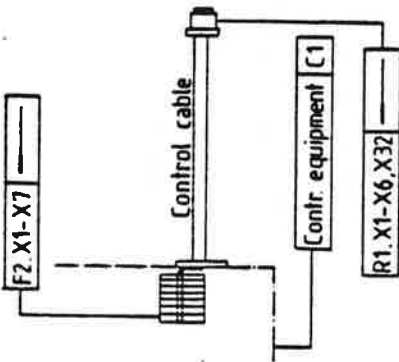
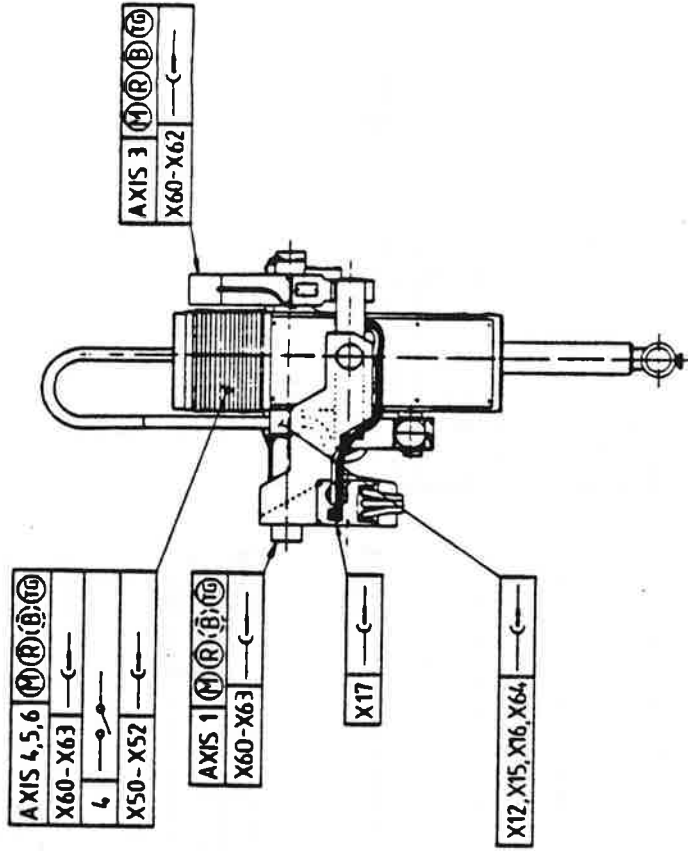


Sheet Contents

- 2-5 Control cable
- 6 Axis 1, Axis 2
- 7 Axis 3, Customer connection IRB 1 - IRB8
- 8,9 X2, X5, X6, X32 — X12, X15, X16
- 10 Axis 4
- 11 Axis 5, Axis 6
- 12 Customer connection IRB9 - IRB20



Review: Location axis connectors (—C—) and switches (—o—)

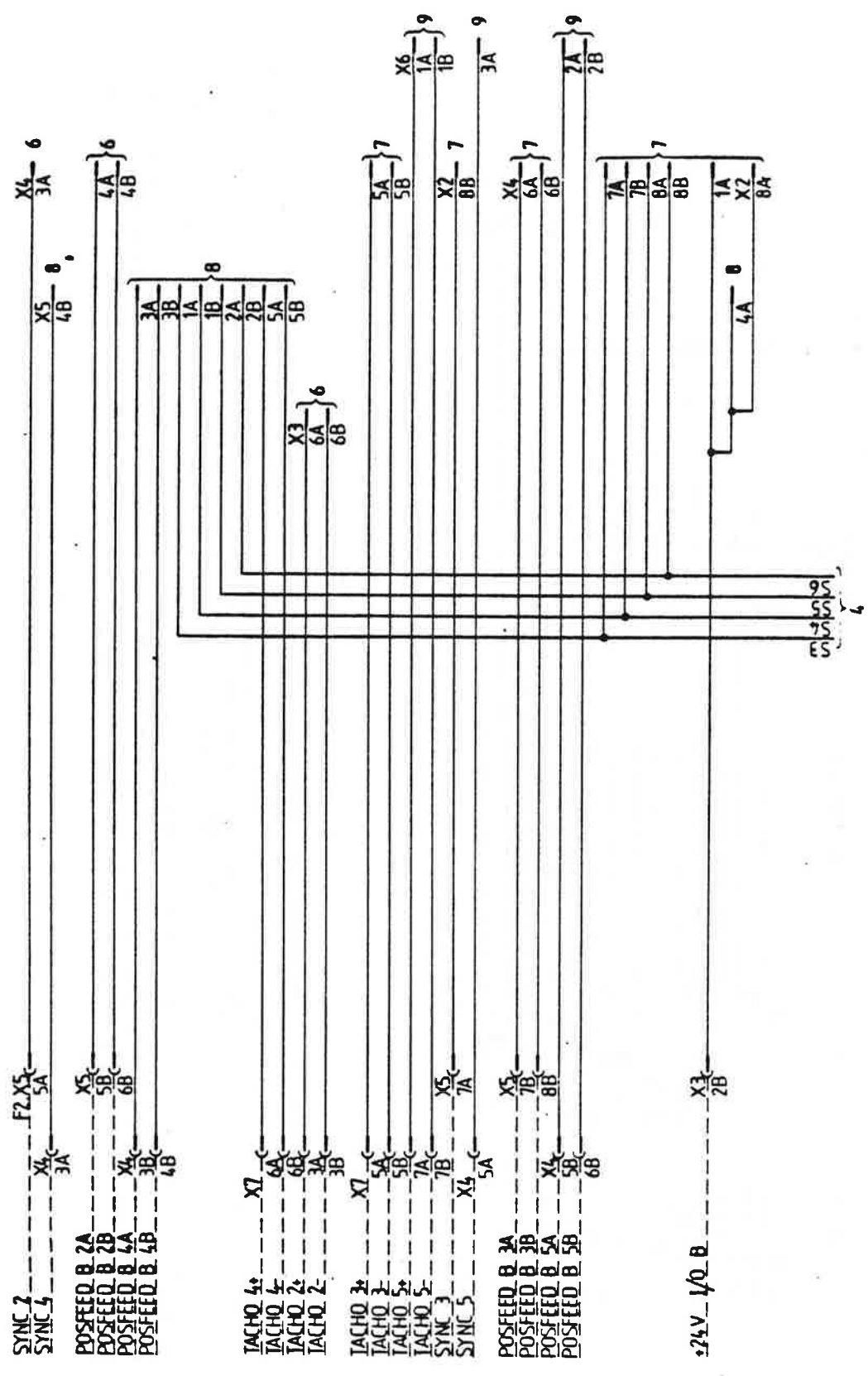


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CONTROL EQUIPMENT C1 CONTROL CABLE C2



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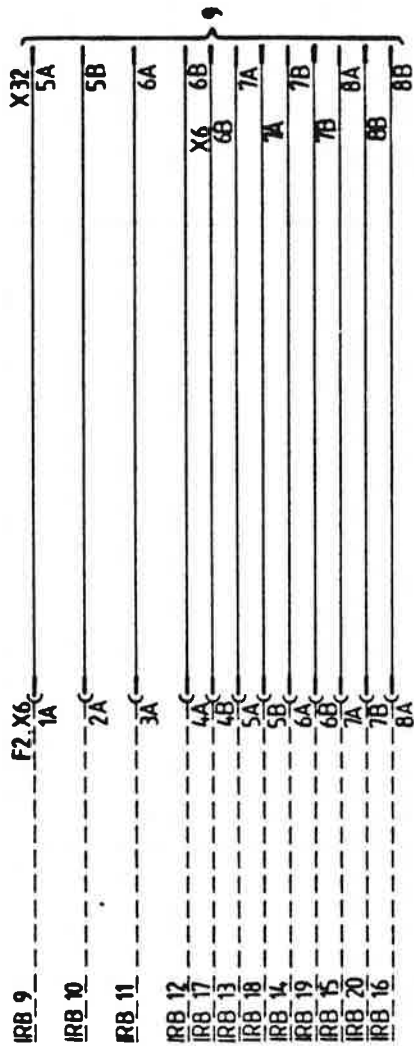
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CONTROL EQUIPMENT C1 CONTROL CABLE C2



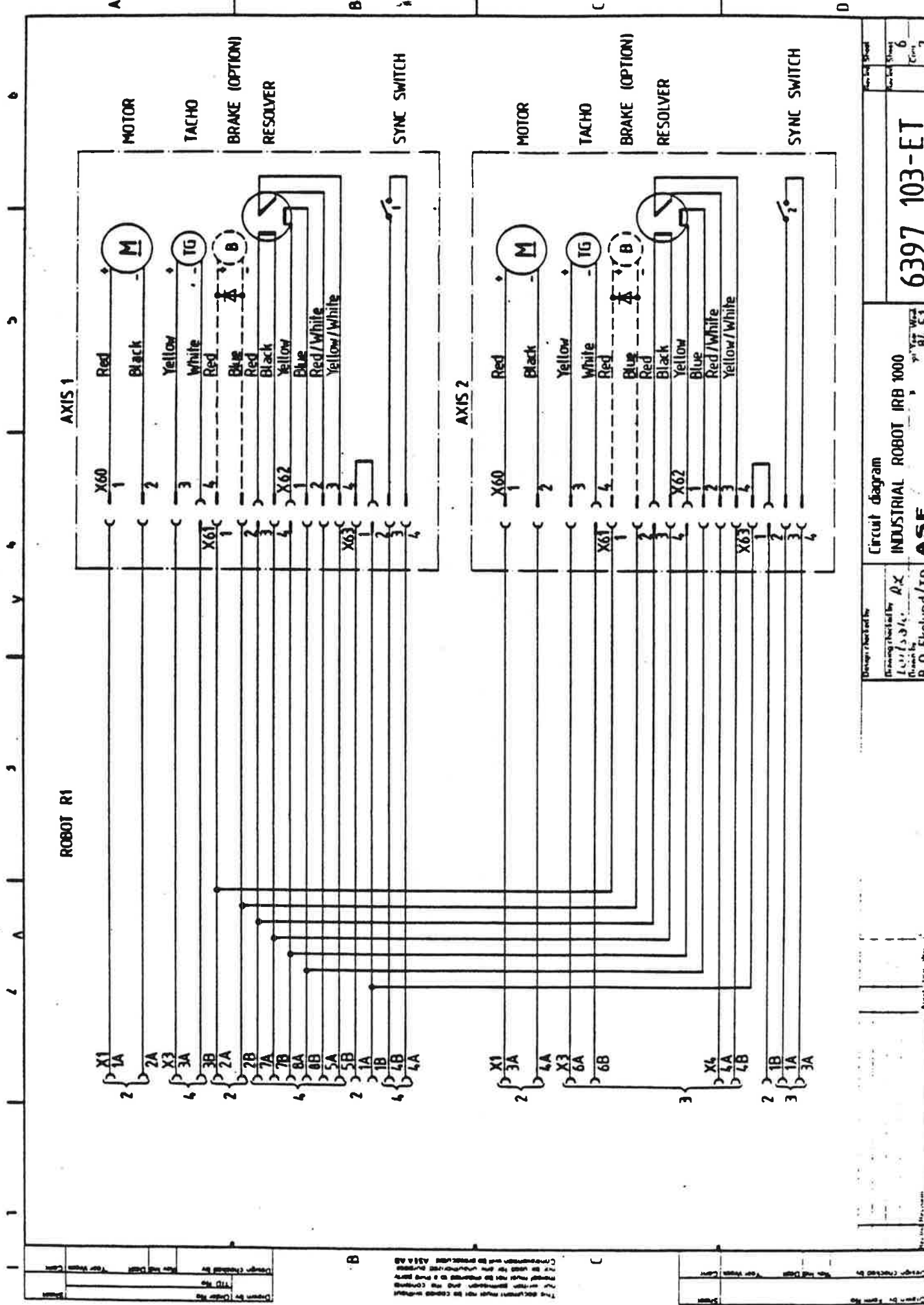
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Project Name	INDUSTRIAL ROBOT IRB 1000
Project Manager	JDK 84 51
Project Start	5
Project End	6
Project Status	5
Project Cost	6

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6397 103-ET

INDUSTRIAL ROBOT IRB 1000

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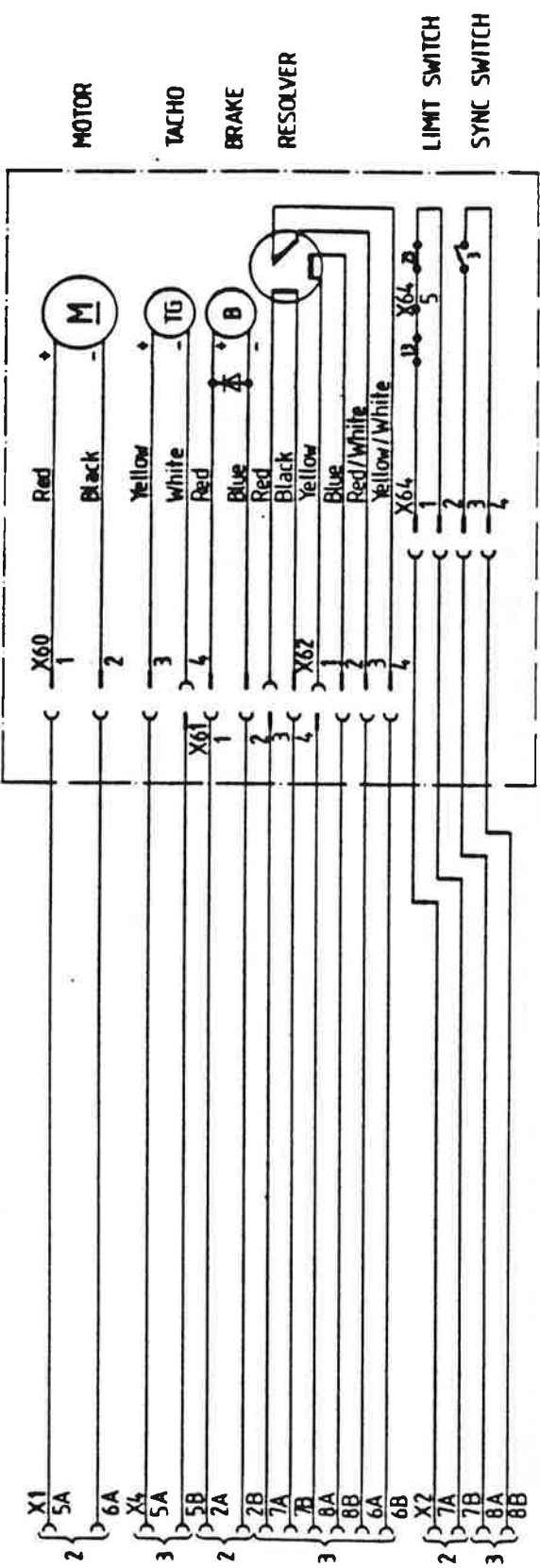
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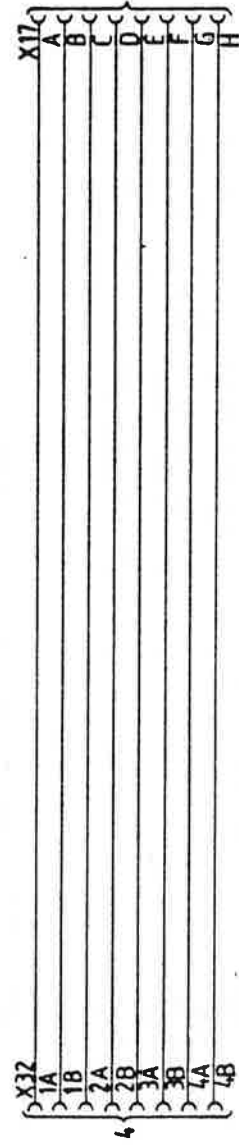
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ROBOT R1

AXIS 3



Customer connection
IRB 1 - IRB 8



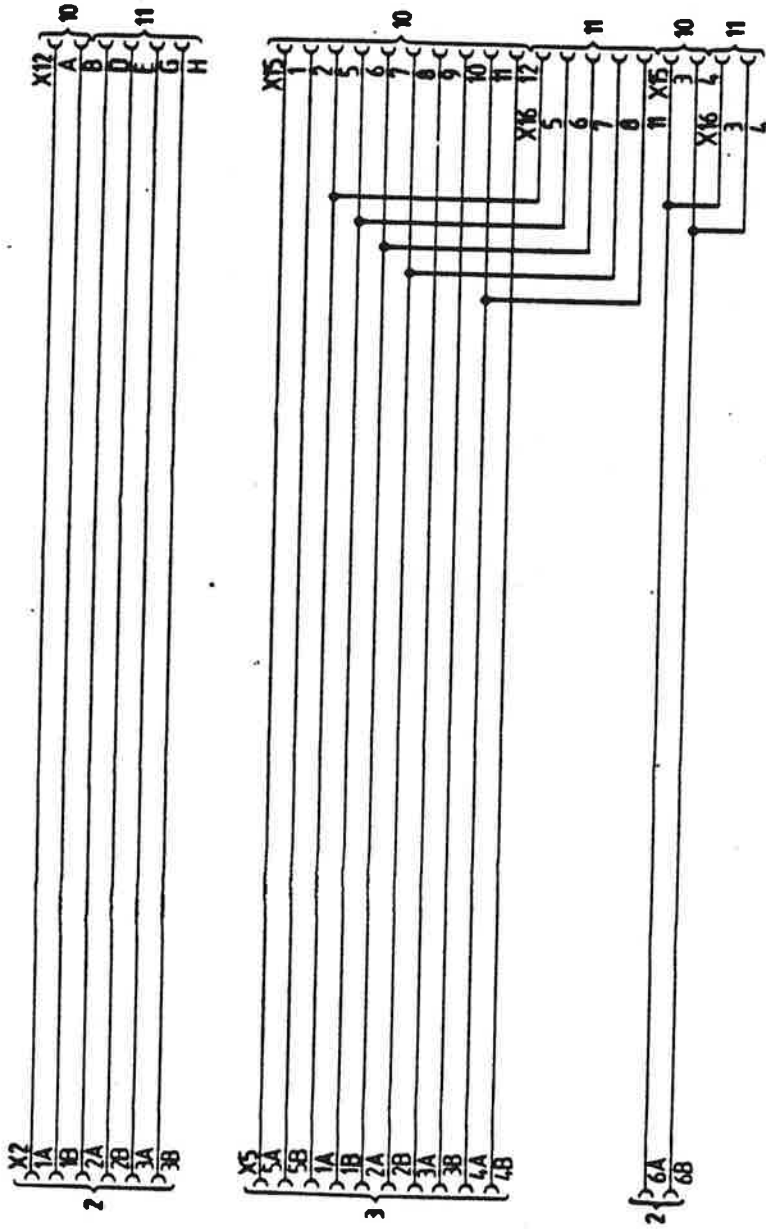
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B-O Ekelund/TP		JOK 84 51	
6397 103-ET		6	

ROBOT R1



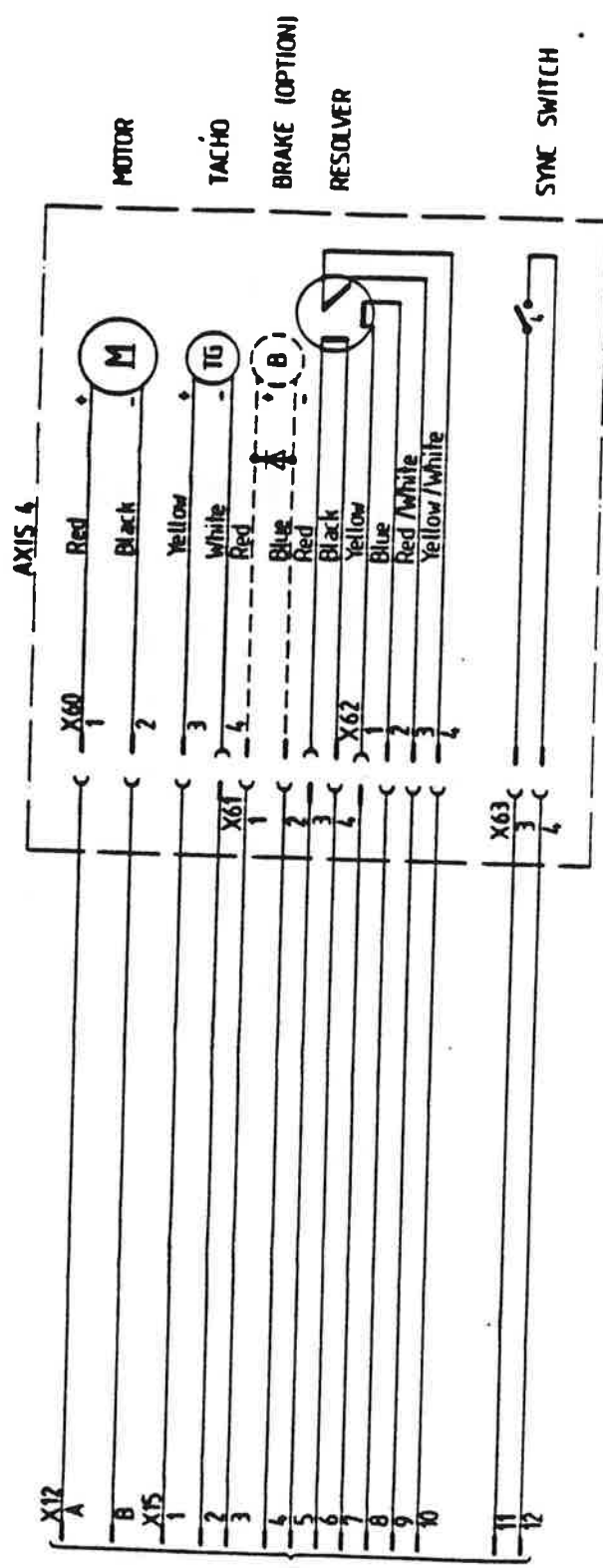
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ROBOT R1



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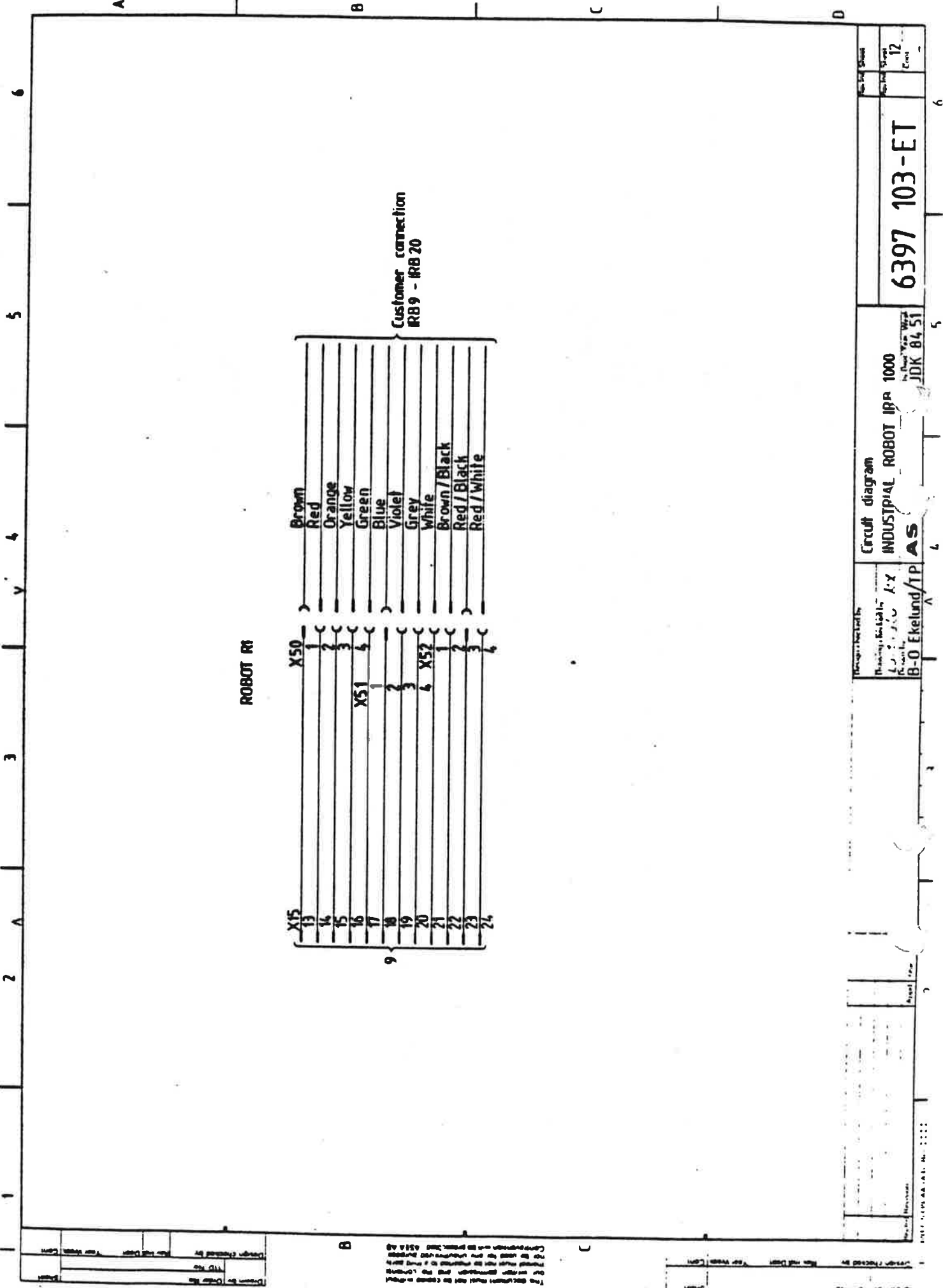
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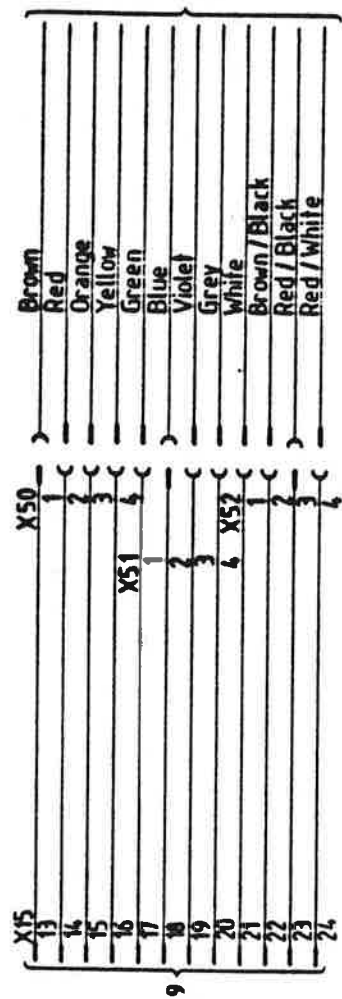
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 INDUSTRIAL ROBOT IRB 1000
 ASE 1

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ROBOT R1



Customer connection
RRB 9 - RRB 20

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Project No.	6397 103-ET
Rev.	12
Project Name	INDUSTRIAL ROBOT IPR 1000
Project No.	JDK 84.51
Project Name	Circuit diagram
Project No.	A-X
Project Name	B-O Ekelund/IP AS